HAOZHI ZHANG

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Objective

Interested in any software development engineering position, especially in robotic/autonomous driving systems.

Education

Master of Science: Robotics Northwestern - Evanston, IL 09/2021 - 12/2022(expected)

GPA 3.75/4.00

Bachelor of Science: Mechanical Engineering **North Carolina State University** - Raleigh, NC GPA 3.98/4.00

08/2016 - 05/2020

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Professional Experience

Intern 11/2020 to 05/2022

Sylincom - Beijing

 Engage in developing an intelligent system embedded on an autonomous agricultural machine using ROS and C++.

Projects

Details available on https://jameszhz1647.wixsite.com/haozhizhang

• Wheel of Despair (04/2019 - 05/2019)

o Design of high-performance controller using control theory in Matlab/Simulink

• UAV Comp (09/2019 - 12/2019)

o Design an unmanned aerial vehicle with remote control and Pixhawk

• Balanced Board (10/2021 - 12/2021)

 Use ROS control to manipulate the Franka robot arm to control a ping-pong ball in order to follow a desired trajectory on a balanced board.

Mobile Manipulation

(11/2021 - 12/2021)

o Control KUKA youBot to pick up a block at the initial location to desired place in simulation.

• Jack in the Box (11/2021 - 12/2021)

o A physical simulation of a jack inside a box. The box is shaken under an external force. The jack will then fall due to gravity, hit the box, and bounce back.

Skilla

Python

ROS

C

• Linux

• C++

Git